

# Near Optimal Channel Assignment for Interference Mitigation in Wireless Mesh Networks

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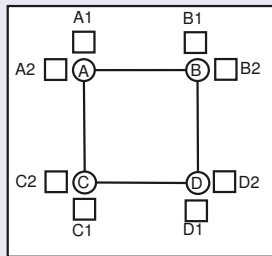
# Wireless Mesh Networks (WMNs)

## A Promising Technology

### MRMC WMNs

- Multi-hop relaying is a primary characteristic of Wireless Mesh Networks (WMNs).
- Wireless transmissions give rise to transmission conflicts, when transmission is occurring on overlapping channels.
- The adverse impact of prevalent interference caused by transmission conflicts devours the network capacity of MRMC WMNs.
- Interference mitigation techniques include channel assignment (CA) to radios, link-scheduling, routing and beam-forming through directional antennas.

### 2\*2 Grid MR WMN



# Role of CA schemes in WMNs

- Interference → Most debilitating factor in network performance.
- Minimizing interference in WMNs is a primary objective.
- Mainly achieved through a prudent channel assignment (CA) scheme, which
  - Enhances network capacity.
  - Reduces end-to-end latency.
  - Reduces data packet loss.
- Optimality is a desired yet elusive goal in real-time deployments.

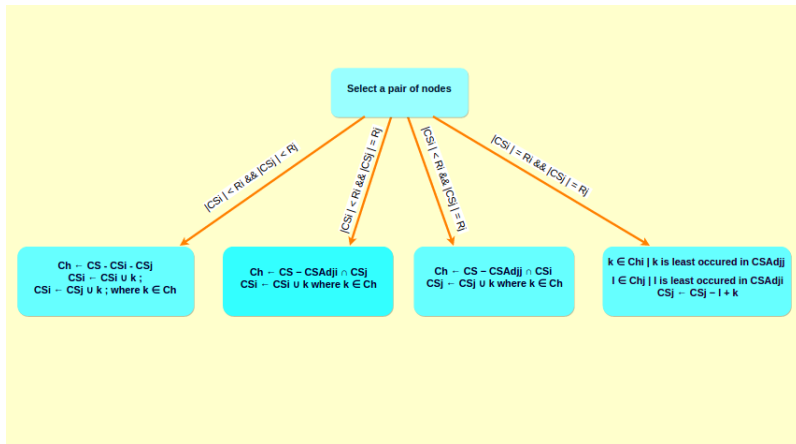
# Terminology

- Network topology is given by  $G_{WMN} = (V_{WMN}, E_{WMN})$ ,  $V_{WMN}$  denotes nodes in the WMN, and  $E_{WMN}$  denotes links in the WMN.
- $CS$  denotes the set of available channels.
- $CS_i$  represents the set of channels that are assigned to the radios on  $i^{th}$  node.
- $cs_{max}$  is the maximum number of available orthogonal channels.
- $R_i$  represents the maximum number of radios on node  $i$ .
- $|CS_i|$  denotes the cardinality of the set  $CS_i$ .

## Why another CA?

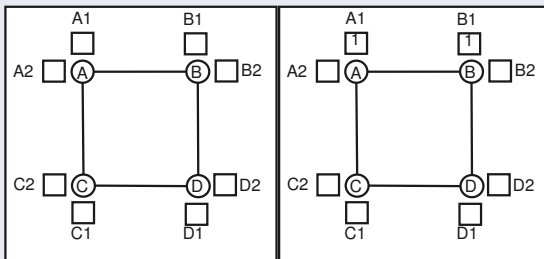
- CA in WMNs is an NP-Hard problem.
- Many algorithms have been proposed, which have high computational overhead and perform worse as compared to brute force(BF).
- For real-time deployments, optimality is a desired yet elusive goal.
- Proposed NOCAG algorithm, is a heuristic with less computational overhead and performs as good as BF.

# Proposed NOCAG algorithm



# Walk Through Example

## Step 1

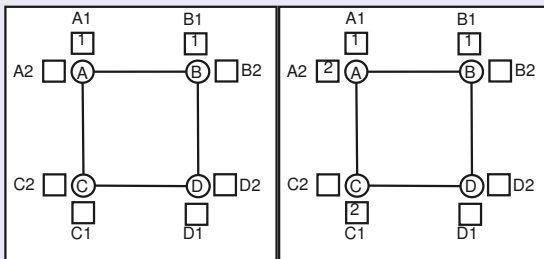


- Chooses nodes A and B
- Assigns channel 1 to radios  $A_1$  and  $B_1$ .



# Walk Through Example

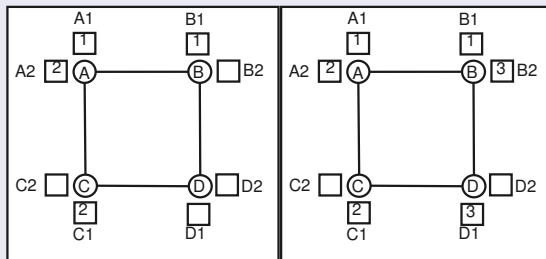
## Step 2



- Chooses nodes A and C
- Assigns channel 2 to radios  $A_2$  and  $C_1$ .

# Walk Through Example

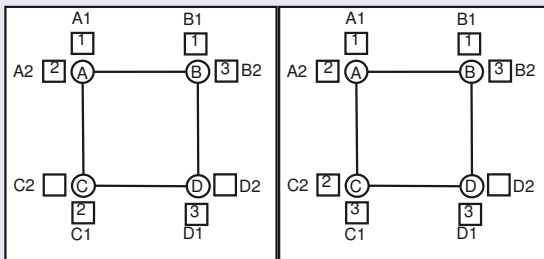
## Step 3



- Chooses nodes B and D.
- Assigns channel 3 to radios  $B_2$  and  $D_1$ .

# Walk Through Example

## Step 4



- Chooses nodes C and D.
- Assigns channel 3 to radios  $C_2$ .

## Time Complexity Analysis

- For a  $n \times n$  grid, let  $m$  be the total number of nodes i.e.,  $m = n^2$ .
- Let  $k$  be the average number of radios on each node and  $c$  be the number of available channels.
- Time complexity BFCA is  $O(c^{(m*k)})$ .
- NOCAG chooses each node at a time and for each node it considers only its adjacent nodes.
  - Maximum number of adjacent nodes can be 4.
  - In the worst case it checks all  $c$  available channels.
- Time complexity for NOCAG is  $O(4 * m * c)$  i.e.,  $O(m * c)$ .
- For regular WMNs  $c \ll m$ .
- So the time complexity is as low as  $O(m)$ .

# MILP Model

- Throughput of the network is considered as a flow problem in a graph.
  - Nodes in the network as the vertices in the graph.
  - Links in the network as the edges in the graph.
  - Max. capacity of the link is analogous to the maximum flow the corresponding edge can carry.
- A MILP model is developed to solve the problem flow problem.
- Model calculates the maximum achievable throughput in the network theoretically.
  - I.e., maximum achievable flow in the analogous graph.
  - Constraints and flow equations are described below.

# MILP Model

- Variables Used:

- $flow(i, j)$  - variable denoting the amount of data flowing from node  $i$  to node  $j$ , on the link connecting  $i$  and  $j$  and its value is 0 if the nodes are not connected.
- $C(i, j)$  - the maximum rate at which the link between node  $i$  and node  $j$  can transfer the data.
- $Rad_{max}$  - number of maximum radios on any node.
- $int$  - represents an intermediate node in a path from source to sink.

# MILP Model

- Constraints:

- *Continuity*: At any intermediate node data incoming is equal to data outgoing.
- *Flow*: The flow on any link is non negative.

$$flow(i, j) \geq 0$$

- Objective: To maximize the flow in the network.

$$Max.Flow = Maximize \sum_k y_k \quad (1)$$

- $y_k$  is the throughput of flow between a source-sink pair.
- $k$  denotes the source-sink pairs in the network.

$$y_k = \frac{1}{|P^k|} \sum_i P_i^k \quad (2)$$

- $P_i^k$  denotes  $i^{th}$  possible path between source-sink pair  $k$ .

$$\begin{aligned}\max P_i^k &= \min\{flow_{max}(source, int_1), \dots, \\ &\quad flow_{max}(int_n, sink)\} \\ &= \min\{C(source, int_1), \dots, C(int_n, sink)\}\end{aligned}\tag{3}$$

$$Max.Flow = \max \sum_k y_k = \sum_k \frac{1}{|P_i^k|} \left( \sum_i \max P_i^k \right)\tag{4}$$



# Test Scenarios & Evaluation Procedure

## Simulation Parameters

### ns-3 Simulation Parameters

Parameter	Value
Available Orthogonal Channels	3
Transmitted File Size	5 MB
Maximum 802.11g/n Phy Datarate	54 Mbps
Maximum Segment Size (TCP)	1 KB
Packet Size (UDP)	512 Bytes
MAC Fragmentation Threshold	2200 Bytes
RTS/CTS	Enabled
TCP NS-3 Protocol	BulkSendApplication
UDP NS-3 Protocol	UdpClientServer
Routing Protocol Used	OLSR
RTS/CTS (TCP)	Enabled
RTS/CTS (UDP)	Disabled
Rate Control	Constant Rate (54Mbps)

# Theoretical Metrics

## Cumulative X-Link-Set Weight ( $CXLS_{wt}$ )[2]

- Considers statistical characteristics and spatial proximity of links for interference estimation.
- Computed by finding all the X-links present in the topology and assigning them a weight based on the CA .
- $CXLS_{wt}$  is the sum of weights of all the X-links.

## Channel Fairness Analysis

- It is a good idea to use all the available channels evenly.
- For this statistical evenness of the channels is calculated.
- Simply the number of links which communicate on a particular channel should almost be the same for all the channels.

$CXLS_{wt}$  Metric

Grid /CA	NOCAG	BF	EIZM[10]	CCA[3]
3x3	14	15	11	8.5
4x4	34	36	28.5	15
5x5	62	68	50.5	33
6x6	98	107	67.5	60.5
7x7	142	151	96	83

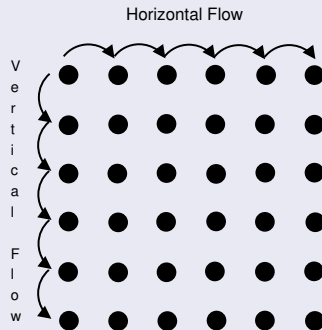
## Channel Fairness Analysis

Grid/CA	NOCAG	BF	EIZM	CCA
3x3	06:06:06	06:06:06	07:05:06	08:01:09
4x4	09:11:12	11:11:10	11:09:12	16:08:08
5x5	15:17:18	16:17:17	16:15:19	25:07:18
6x6	22:24:26	24:24:24	21:21:30	36:12:24
7x7	31:33:35	33:33:32	32:28:38	47:13:38

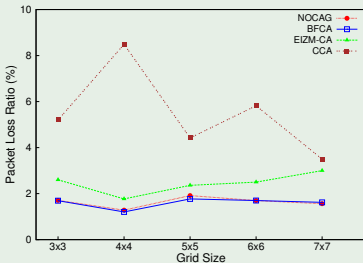
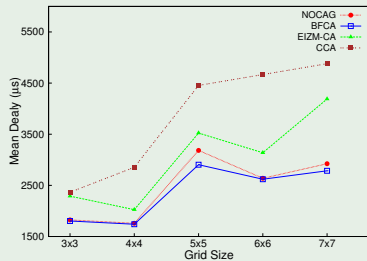
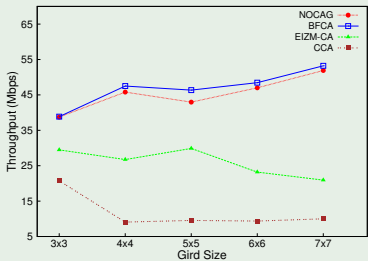
## Test scenario

- We develop a test scenario that includes each and every node for data transmission in the WMN.
- Consider a  $n \times n$  grid, we establish  $2n$  concurrent flows,  $n$  vertical flows and  $n$  horizontal flows.
- Setup ensures that the nodes are exhaustively involved in data transmission ideal to assess the performance of the CA.

## 6x6 Grid WMN



# Experimental Results



## Throughput in Mbps

Grid Size	MILP Max. Value	BF Exp. Value	NOCAG Exp. Value
3×3	54.6	38.87	38.74
4×4	72.8	47.50	45.80
5×5	91	46.36	42.97
6×6	109.2	48.46	47.00
7×7	127.4	53.21	51.90

# Conclusions

- Computational overhead is linear in terms of the number of nodes in the network.
- A very high performance hike is observed and is very close to the brute force CAs and much better than existing CAs.
- Channel Fairness is better than compared to existing CAs and is very close to BFCA.
- Algorithm is intelligent and is easy to implement.



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# THANK YOU

# QUERIES ?